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随机激励下自复位结构首次穿越失效研究*

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摘要 自复位结构遭受地震或强风荷载时,会发生显著的非线性随机振动,这可能导致结构的运行性能大 大降低,甚至完全失效.本文旨在研究随机激励下双自由度自复位结构的首次穿越失效问题.应用广义谐波 平衡技术,将自复位恢复力进行分解,获得等效随机系统;利用随机平均原理推导出关于幅值的平均 Itô 随 机微分方程;求解后向 Kolmogorov(BK)方程得到首次穿越时间的条件可靠性函数和条件概率密度函数通 过.作为算例,选用金井清滤波白噪声模型,分析了激励强度 D 及土层阻尼比 *ξ*_g 取值变化时对条件可靠性 函数和条件概率密度函数的影响.通过与 Monte Carlo 模拟得到的结果进行对比,验证了解析解的有效性.

关键词 自复位结构,双自由度,随机平均法,首次穿越失效,金井清过滤白噪声激励 中图分类号:O324
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First-Passage of Self-Centering System Under Random Excitation*

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Abstract When the self-centering structure is subjected to earthquake or strong wind load, significant nonlinear random vibration will occur, which may lead to the structural performance greatly reduced or even complete failure. In this paper, the first-passage failure problem of a self-centering structure with two-degrees-of-freedom under random excitation is studied. The generalized harmonic balance technique is used to decompose the self-centering restoring force and obtain the equivalent random system. The average Itô stochastic differential equation with respect to amplitude is derived by means of stochastic average method. The backward Kolmogorov (BK) equation is solved to obtain the conditional reliability function (CRF) and conditional probability density function of the first pass time (PDF). As an example, Kanai-Tajimi filtered white noise model is used to analyze the influence of the change of excitation strength Dand soil damping ratio ξ_g on conditional reliability function and conditional probability density function. The validity of the analytical solution is verified by comparing with Monte Carlo simulation results.

Key words self-centering structure, two degrees of freedom, stochastic average method, first-passage failure, Kanai-Tajimi filtered white noise excitation

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引言

地震作为一种常见的自然灾害,给人类社会带 来的损害难以想象.传统的抗震设计方法确保结构 具有足够的延性和消能能力,但对于控制地震后的 残余变形及其带来的损坏还未能达到预期的目 标^[1,2].因此,在实际工程中迫切需要提高工程结构 的恢复能力和抗震性能.自复位结构作为一种新型 抗震结构,在过去十几年中得到了广泛研究^[3-10]. 研究结果表明,自复位结构在地震作用下可以提高 结构的复位能力,减小结构的残余变形,降低结构 的修复成本.

首次穿越失效是非线性随机振动中最主要同 时也是最困难的问题之一,它是研究结构可靠度以 及预测结构寿命的基础,到目前为止,已经提出了 多种方法来研究首次穿越失效问题,例如,Zeng 等[11]采用蒙特卡洛模拟法研究了泊松白噪声和随 机激励下滞回系统的平稳响应和首次穿越失效: Chen 等^[12]利用随机扩散原理,得到了多自由度非 线性结构的随机动力响应概率密度函数,进而得到 单一失效模式的结构动力可靠度;Engelund 等[13] 运用级数展开方法,得到了结构首次穿越失效概率 的上下界 以上这些方法虽能有效研究首次穿越失 效问题,但仍存在计算过程复杂、计算量大、效率低 等不足.因此,发展一种可行且高效的方法来研究 结构的首次穿越失效问题成为目前的关注重点.随 机平均法作为研究随机强非线性系统的有效方法 之一,目前得到了广泛的关注和应用[14-19].一方 面,经过随机平均处理后,随机微分方程的维数大 大降低,便于求解后向 Kolmogorov 方程:另一方 面,经过平均处理后,随机系统对非高斯白噪声激 励的响应在一定条件下可近似为扩散的 Markov 过程,扩大了这一理论分析方法的适用范围.近年 来,张雷等[20]运用随机平均法,研究了高斯白噪声 激励下多自由度强非线性随机振动系统的首次穿 越:Zhu 等[21,22] 应用随机平均法,研究了随机地震 激励下多自由度拟可积/拟不可积哈密顿系统的首 次穿越.研究表明,随机平均法的应用大大减小了 计算量,使得效率得到了很大的提升,因此,这一方 法已成为近几十年来研究首次穿越失效问题的主 要方法.例如,曾岩等^[23]、Chen 等^[24]、Wu 等^[25]运 用随机平均法分别研究了非高斯激励下双线性滞 迟系统和 Bouc-Wen 滞迟系统这两类经典滞迟系

统、具有分数阶导数阻尼的单自由度非线性振子、 谐和与真实噪声激励下强非线振子的首次穿越失 效问题,并均与 Monte Carlo 模拟结果进行对比, 验证了所用理论分析方法的可行性.

本文研究了随机激励下双自由度自复位结构 的首次穿越失效问题.在理论分析中,首先利用广 义谐波平衡技术将旗帜形恢复力解耦为等效阻尼 和等效刚度,得到与原系统等效的非线性随机系 统,再经过随机平均进一步简化为扩散过程.随后, 求解由平均伊藤方程建立的后向 Kolmogorov (BK)方程,得到条件可靠性函数和条件概率密度 函数.最后,研究了激励强度 D 及土层阻尼比 ξ_g 对 系统可靠性的影响.通过与 Monte Carlo 模拟数据 的对比,验证了所提方法的有效性和实用性.

1 理论分析

考虑随机激励下双自由度自复位系统,其运动 微分方程可表示为:

$$m_{1}\ddot{Y}_{1} + (c_{1} + c_{2})\dot{Y}_{1} + k_{2}Y_{1} + F(Y_{1}, \dot{Y}_{1}) - c_{2}\dot{Y}_{2} - k_{2}Y_{2} = -m_{1}\xi(t)$$

$$m_{2}\ddot{Y}_{2} + c_{2}\dot{Y}_{2} + k_{2}Y_{2} - c_{2}\dot{Y}_{1} - k_{2}\dot{Y}_{1} = -m_{2}\xi(t)$$
(1)

其中, k_i 为质量 m_i 的刚度系数; c_i 为质量 m_i 的阻 尼系数; $\xi(t)$ 为随机激励; $F(Y_1, \dot{Y}_1)$ 为自复位恢复 力; $Y_1, \dot{Y}_1, \ddot{Y}_1$ 分别为位移、速度、加速度.



(3)

大量试验证明地震作用下自复位结构的力-位 移关系曲线呈旗帜形^[26-28],如图 1 所示.其中 Y_y 为系统的屈服位移,F_y为系统的屈服力;α 表示消 能单元的屈服后刚度系数.

旗帜形恢复力可分解为弹性力(图 1(b))和滞回力(图 1(c)):

$$F(Y, \dot{Y}) = \alpha Y + (1 - \alpha)Z$$
 (2)
其中,Z 为旗帜形模型的滞变位移(图 2), α 为能量
耗散系数.

滞变位移 Z 可表示为以下的分段函数形式:



图 2 自复位体系滞变位移 Fig.2 The hysteretic displacement of the self-centering system

	$\int -Y_y$	$-A \leqslant Y < -Y_y$
$Z = \langle$	Y	$-Y_{y} \leqslant Y < Y_{y} - \beta Y_{y}$ $\dot{V} < 0$
	$Y_y - \beta Y_y$	$Y_{y} - \beta Y_{y} \leqslant Y < A - \beta Y_{y}, I < 0$
	$Y + Y_y - A$	$A - \beta Y_{y} \leqslant Y < A$
$Z = \cdot$	$\int Y - Y_y + A$	$-A \leqslant Y \mathop{<}-A + \beta Y_{\scriptscriptstyle \mathcal{Y}}$
	$\int -Y_{y}+\beta y_{y}$	$-A + \beta Y_{y} \leqslant Y < -Y_{y} + \beta Y_{y}$ $\dot{Y} > 0$
	Y	$-Y_{y} + \beta Y_{y} \leqslant Y < Y_{y} \qquad , Y \geqslant 0$
	Y_y	$Y_{y} \leqslant Y < A$

其中,A、Y_y、β分别表示系统位移幅值、屈服位移 和能量耗散系数.

$$f(Y, \dot{Y}) = \begin{cases} \alpha Y - (1 - \alpha)Y_{y} \\ Y \\ \alpha Y - (1 - \alpha)(Y_{y} - \beta Y_{y}) \\ \alpha Y - (1 - \alpha)(Y + Y_{y} - A) \end{cases}$$
$$f(Y, \dot{Y}) = \begin{cases} \alpha Y - (1 - \alpha)(Y - Y_{y} + A) \\ \alpha Y - (1 - \alpha)(-Y_{y} + \beta y_{y}) \\ Y \\ \alpha Y - (1 - \alpha)Y_{y} \end{cases}$$

由图 1 可知,恢复力不仅对阻尼有贡献,对系统刚 度也有贡献.引入广义谐波平衡技术,即:

$$Y(t) = A(t)\cos\Phi'(t)$$

$$\dot{Y}(t) = -A(t)\omega(A)\sin\Phi'(t)$$
(5)

其中, $\Phi'(t) \approx \omega t + \Phi$.旗帜形恢复力可解耦为幅 值依赖的等效刚度和等效阻尼.结果为:

$$F(Y, \dot{Y}) \approx K_1(A)Y + C(A)\dot{Y}$$
 (6)
式中, $K_1(A)$ 表示等效刚度系数, $C(A)$ 表示等效
阻尼系数,表达式分别为:

$$K_1(A) = \frac{1}{\pi A} \int_0^{2\pi} (A \cos \Phi', -A\omega \sin \Phi') \cos \Phi' d\Phi' =$$

将式(3)代入式(2)中,可得旗帜形恢复力的表 达式为:

$$-A \leqslant Y < -Y_{y}$$

$$-Y_{y} \leqslant Y < Y_{y} - \beta Y_{y}, \quad \dot{Y} < 0$$

$$Y_{y} - \beta Y_{y} \leqslant Y < A - \beta Y_{y}, \quad \dot{Y} < 0$$

$$A - \beta Y_{y} \leqslant Y < A$$

$$-A \leqslant Y < -A + \beta Y_{y}$$

$$-A + \beta Y_{y} \leqslant Y < -Y_{y} + \beta Y_{y}, \quad \dot{Y} \ge 0$$

$$Y_{y} \leqslant Y < A$$

$$Y_{y} \leqslant Y < A$$

$$(4)$$

$$\begin{cases} 1 & A \leqslant Y_{y} \\ \frac{(\Omega_{1} + \Omega_{2} + \Omega_{3} + \Omega_{4})}{\pi} & A > Y_{y} \end{cases}$$

$$C(A) = \frac{1}{\pi A \omega} \int_{0}^{2\pi} F(A \cos \Phi', -A \omega \sin \Phi') \sin \Phi' d\Phi' = \\ \begin{cases} 0 & A \leqslant Y_{y} \\ \frac{2(\alpha - 1)(A - Y_{y})\beta Y_{y}}{\pi \omega A^{2}} & A > Y_{y} \end{cases}$$

$$(7)$$

式中, $\omega = \sqrt{K_1(A)}$ 为系统平均频率, $\Omega_1 - \Omega_4$ 及 $\varphi_1 - \varphi_3$ 的具体表达式如下:

$$\begin{split} \Omega_{1} &= \pi - \varphi_{2} - \varphi_{1} + \frac{1}{2} \sin 2(\pi - \varphi_{2}) - \frac{1}{2} \sin(2\varphi_{1}) \\ \Omega_{2} &= \frac{1}{2} \alpha \left[\sin(2\varphi_{2}) + 2\varphi_{2} \right] - \frac{2}{A} (1 - \alpha) Y_{y} \sin\varphi_{2} \\ \Omega_{3} &= \frac{1}{2} \alpha \left[\sin(2\varphi_{1}) - \sin(2\varphi_{3}) \right] + \frac{2}{A} (1 - \alpha) \cdot \\ (1 - \beta) (\sin\varphi_{1} - \sin\varphi_{3}) Y_{y} + \alpha (\varphi_{1} - \varphi_{3}) \\ \Omega_{4} &= \frac{1}{2} \sin(2\varphi_{3}) + \varphi_{3} + \frac{2}{A} (1 - \alpha) (Y_{y} - A) \sin\varphi_{3} \\ \varphi_{1} &= \arccos \left[\frac{(1 - \beta) Y_{y}}{A} \right] \\ \varphi_{2} &= \arccos \left[\frac{(1 - \beta) Y_{y}}{A} \right] \\ \varphi_{3} &= \arccos \left[\frac{A - \beta Y_{y}}{A} \right] \end{split}$$
(8)

$$\neq c = \frac{1}{2} \cos \left(\frac{A - \beta Y_{y}}{A} \right)$$

 $m_{1}\ddot{Y}_{1} + [c_{1} + c_{2} + C(A_{1})]\dot{Y}_{1} + [k_{2} + K_{1}(A_{1})]Y_{1} - c_{2}\dot{Y}_{2} - k_{2}Y_{2} = -m_{1}\xi(t)$ $m_{2}\ddot{Y}_{2} + c_{2}\dot{Y}_{2} + k_{2}Y_{2} - c_{2}\dot{Y}_{1} - k_{2}Y_{1} = -m_{2}\xi(t)$ (9)

设系统(9)有如下形式的解: $Y_i(t) = A_i(t) \cos \Phi_i(t)$

 $\dot{Y}_{i}(t) = -A_{i}(t)\omega_{i}(A_{i},\Theta_{i})\sin\Phi_{i}(t)$ (10) 式中, $\Phi_{i}(t) \approx \omega_{i}(A)t + \Theta_{i}(t);A_{i}(t),\Phi(t),$ $\Theta_{i}(t)$ 均为随机过程.

式(10)可看作 $[Y_i, \dot{Y}_i]^T$ 到 $[A_i, \Theta_i]^T$ 的广义 范德波变换,将式(10)代入式(9),得到关于 $[A_i, \Theta_i]^T$ 的随机微分方程组,

$$\frac{dA_1}{dt} = F_{11}(A_1, \Phi_1) + G_{11}(A_1 + \Phi_1)\xi(t)$$

$$\frac{d\Phi_1}{dt} = F_{21}(A_1, \Phi_1) + G_{21}(A_1 + \Phi_1)\xi(t)$$

$$\frac{dA_2}{dt} = F_{12}(A_1, \Phi_1) + G_{12}(A_1 + \Phi_1)\xi(t)$$

$$\frac{d\Phi_2}{dt} = F_{22}(A_1, \Phi_1) + G_{22}(A_1 + \Phi_1)\xi(t)$$

式中

$$G_{11} = \frac{\sin\Phi_1}{\omega_1}, G_{21} = \frac{\cos\Phi_1}{A_1\omega_1}$$
$$G_{12} = \frac{\sin\Phi_2}{\omega_2}, G_{22} = \frac{\cos\Phi_2}{A_1\omega_2}$$
$$F_{11} = -A_1\omega_1\sin\Phi_1\cos\Phi_1 -$$

$$\frac{[c_1+c_2+C(A_1)]A_1\sin^2\Phi_1}{m_1} + \frac{c_2A_2\omega_2}{m_1\omega_1}\sin\Phi_1\sin\Phi_2 +$$

$$\frac{m_1\omega_1}{\sum_{i=1}^{m_1\omega_1}} \frac{\left[k_2 + K_1(A_1)\right]A_1}{m_1\omega_1} \sin\Phi_1\cos\Phi_1 - \frac{k_2A_2}{m_1\omega_1}\sin\Phi_1\cos\Phi_2$$
$$F_{21} = -\omega_1\cos^2\Phi_1 - \frac{\left[c_1 + c_2 + C(A_1)\right]\sin\Phi_1\cos\Phi_1}{m_1}$$

$$+$$

$$\frac{c_{2}A_{2}\omega_{2}}{m_{1}A_{1}\omega_{1}}\sin\Phi_{2}\cos\Phi_{1} + \frac{[k_{2} + K_{1}(A_{1})]}{m_{1}\omega_{1}}\cos^{2}\Phi_{1} - \frac{A_{2}k_{2}}{m_{1}A_{1}\omega_{1}}\cos\Phi_{1}\cos\Phi_{2}$$

$$F_{12} = -A_{2}\omega_{2}\sin\Phi_{2}\cos\Phi_{2} + \frac{c_{2}A_{1}\omega_{1}}{m_{2}\omega_{2}}\sin\Phi_{1}\sin\Phi_{2} - \frac{c_{2}A_{2}\sin^{2}\Phi_{2}}{m_{2}} - \frac{A_{1}k_{2}}{m_{2}\omega_{2}}\cos\Phi_{1}\sin\Phi_{2} + \frac{k_{2}A_{2}}{m_{2}\omega_{2}}\sin\Phi_{2}\cos\Phi_{2}$$

$$F_{22} = -\omega_{2}\cos^{2}\Phi_{2} + \frac{c_{2}A_{1}\omega_{1}}{m_{2}A_{2}\omega_{2}}\sin\Phi_{1}\cos\Phi_{2} - \frac{c_{2}\sin\Phi_{2}\cos\Phi_{2}}{m_{2}} - \frac{k_{2}A_{1}}{m_{2}A_{2}\omega_{2}}\cos\Phi_{1}\cos\Phi_{2} + \frac{k_{2}}{m_{2}\omega_{2}}\cos\Phi_{2} - \frac{k_{2}A_{1}}{m_{2}\omega_{2}}\cos\Phi_{1}\cos\Phi_{2} + \frac{k_{2}}{m_{2}\omega_{2}}\cos\Phi_{2} - \frac{k_{2}A_{1}}{m_{2}\omega_{2}}\cos\Phi_{2} - \frac{k_{2}A_{1}}{m_{2}\omega_{2}}\cos\Phi_{1}\cos\Phi_{2} + \frac{k_{2}}{m_{2}\omega_{2}}\cos\Phi_{2} - \frac{k_{2}A_{1}}{m_{2}\omega_{2}}\cos\Phi_{1}\cos\Phi_{2} + \frac{k_{2}}{m_{2}\omega_{2}}\cos\Phi_{2} - \frac{k_{2}A_{1}}{m_{2}\omega_{2}}\cos\Phi_{2} - \frac{k_{2}A_{2}}{m_{2}}\cos\Phi_{2} - \frac{k_{2}A_{2}}{m_{$$

根据 Stratonovich-Khasminskii 极限定理^[29], [A_i , Θ_i]^T可以近似为四维 Markov 扩散过程.但需 注意,经过随机平均和确定平均后, $A_i(t)$ 的平均微 分方程独立于 $\Theta_i(t)$.因此,支配极限过程 $A_i(t)$ 的 平均伊藤随机微分方程如下,

$$\mathrm{d}A_{i} = \bar{m}_{i}(A)\,\mathrm{d}t + \bar{\sigma}_{i}(A)\,\mathrm{d}B(t)\,, \quad i = 1,2 \tag{13}$$

其中,B(t)为单位维纳过程,

(11)

$$\bar{m}_{i} = \langle F_{ii} + \int_{-\infty}^{0} \left[\frac{\partial G_{1i}}{\partial A_{i}} \Big|_{t} G_{1i} \Big|_{t+\tau} R(\tau) + \frac{\partial G_{1i}}{\partial \Phi_{i}} \Big|_{t} G_{2i} \Big|_{t+\tau} R(\tau) \right] d\tau \rangle_{\Phi}$$
$$\bar{\sigma}_{i}^{2}(A) = \langle \int_{-\infty}^{\infty} G_{1i} \Big|_{t} G_{1i} \Big|_{t+\tau} R(\tau) d\tau \rangle_{\Phi} \quad (14)$$

式中, $\langle \cdot \rangle_{\Phi} = \frac{1}{(2\pi)^2} \int_{0}^{2\pi} \langle \cdot \rangle d\Phi_1 d\Phi_2; \Phi = [\Phi_1, \Phi_2]^T; R(\tau) 表示系统激励的自相关函数,相应的功$ $率谱函数为 <math>S(\omega) = \frac{1}{\pi} \int_{-\infty}^{0} R(\tau) \cos\omega\tau d\tau.$ 为进一步得到漂移系统与扩散系数的显式表达式,将式(14)中的 G_{ik}展开成 Fourier 级数,

$$\bar{m}_{1} = -\frac{[c_{1} + c_{2} + C(A_{1})]A_{1}}{2m_{1}} - \frac{\pi S_{2}(\omega)}{4[k_{2} + K_{1}(A_{1})]^{2}} \frac{dK_{1}(A_{1})}{dA_{1}} + \frac{\pi S_{2}(\omega)}{2A_{1}[k_{2} + K_{1}(A_{1})]}$$

$$\bar{m}_{2} = \frac{-c_{2}A_{2}}{2m_{2}} + \frac{\pi S_{2}(\omega)}{2A_{2}k_{2}}$$

$$\bar{\sigma}_{1}^{2} = \frac{\pi S_{2}(\omega)}{k_{2} + K_{1}(A_{1})}$$

$$\bar{\sigma}_{1}\bar{\sigma}_{2} = 0, \qquad \bar{\sigma}_{2}^{2} = \frac{\pi S_{2}(\omega)}{k_{2}} \qquad (15)$$

2 首次穿越失效

对建筑结构系统而言,相空间内系统的状态可 用振幅 A 来表示.假设存在某个开区间 Ω_s :(0, A_c)作为式(9)的安全域,系统(9)的位移振幅 $A(t) = [A_1, A_2]^T$ 可在 $[0, \infty)$ 内变化,一旦其达到 或超过临界值 A_c ,系统就发生首次穿越而破坏.因 此,扩散过程(15)的条件可靠性函数可定义为:

 $R(t \mid A_0) = P\{A(\tau) \in \Omega_s, \tau \in (0, t] \mid A_0 \in \Omega_s\}$ (16)

其中 $A_0 = [A_{10}, A_{20}]^T$ 表示系统初始幅值.

根据扩散的 Markov 过程理论,控制条件可靠 性函数的后向 Kolmogorov 方程可表示为:

$$\frac{\partial R(t \mid A_{0})}{\partial t} = \bar{m}_{1}(A_{0}) \frac{\partial R}{\partial A_{10}} + \bar{m}_{2}(A_{0}) \frac{\partial R}{\partial A_{20}} + \frac{1}{2}\bar{\sigma}_{1}^{2}(A_{0}) \frac{\partial^{2} R}{\partial A_{20}^{2}} + \frac{1}{2}\bar{\sigma}_{2}^{2}(A_{0}) \frac{\partial^{2} R}{\partial A_{20}^{2}}$$
(17)

其中,用A₀代替A得到可得到漂移系数与扩散系数.后向 Kolmogorov 方程还满足如下的初始条件与边界条件,

$$R(t \mid A_{0}) = \begin{cases} 0, & A_{10} = A_{1c} \ \vec{x} A_{20} = A_{2c} \\ \text{finite}, & A_{0} = 0 \\ 1, & A_{0} \in \Omega_{s} \end{cases}$$
(18)

在 Crank-Nicolson 隐式格式的有限差分法的帮助下,通过初始条件与边界条件求解后向 Kolmogorov 方程,得到系统的条件可靠性函数.首次 穿越时间的条件概率密度函数可对式(16)进行一 阶求导获得:

$$p(\tau \mid A_0) = -\frac{\partial R(t \mid A_0)}{\partial t} \bigg|_{t=\tau}$$
(19)

3 算例分析

高斯白噪声激励是特殊的宽带噪声激励,且较为理想化,易于进行数学处理.但在实际工程中,较为常见的是随机激励的情况,需将其化为滤波白噪 声激励才更为合理.与高斯白噪声激励有差别的地 方是,此时的功率谱密度 S(ω)不再看作常数.对于 滤波白噪声激励情形,式(9)中随机激励采用金井 清滤波白噪声模型,其功率谱密度为:

$$\mathbf{S}_{2}(\boldsymbol{\omega}) = \frac{\boldsymbol{\omega}_{g}^{4} + 4\boldsymbol{\xi}_{g}^{2}\boldsymbol{\omega}_{g}^{2}\boldsymbol{\omega}^{2}}{(\boldsymbol{\omega}_{g}^{2} - \boldsymbol{\omega}^{2}) + 4\boldsymbol{\xi}_{g}^{2}\boldsymbol{\omega}_{g}^{2}\boldsymbol{\omega}^{2}}\mathbf{S}_{0}$$
(20)

其中,ω_g 与ξ_g 分别为地震波传播过程中所经历土 层的特征频率和阻尼比.



通过无量纲化处理,选取其他系统参数 $m_1 = 1, m_2 = 1.16, \beta_1 = 0.005, \beta = 0.5, \alpha = 0.1, D = 0.01,$ $Y_s = 0.5, c_1 = 0.000763s - 1, c_2 = 0.0763 s - 1,$ $k_2 = 12.57, \omega_g = 10, \xi_g = 0.5. 图 3 ~ 图 4 给出了通$ 过激励强度 <math>D、土层阻尼比 ξ_g 取值的变化对条件 可靠性函数和条件概率密度函数的影响,通过近似 解析结果(实线)与数值模拟结果(符号($\bigcirc, \diamondsuit, \land, \land$))的对比,可以看出两者较为吻合,证明本节求 解方法有效.此外,从图中可看出,条件可靠性函数 均随时间的增加而减小.





图 3(a)与(b)中,考察激励强度 D 对系统可靠 性的影响,其取值为:D=0.01,D=0.02,D=0.04. 从图 3(a)中可看出,随着激励强度 D 的减小,系统 可靠性函数 R(t)=R(t | A₀=0)增大,意味着系统 可靠性的提高;图 3(b)中条件概率密度函数 $p(t) = p(\tau|A_0=0)$ 的峰值随激励强度 D 的减小而减小, 且变化明显,同样说明系统可靠性随激励强度 D 的减小而提高.图 4(a)与(b)中土层阻尼比 ξ_g 取值 为: $\xi_g = 0.3$, $\xi_g = 0.7$, $\xi_g = 1.0$.从图中可看出,与激 励强度的影响效果不同,随着土层阻尼比 ξ_g 取值 的减小,系统可靠性逐渐降低.



amplitudes A_{10} and A_{20} at time t=0.01s

图 5 是系统的条件可靠性函数随初始幅值 $A_{10}和 A_{20}$ 变化的三维图像,可见随着 $A_{10}和 A_{20}$ 靠 近阈值边界,系统的可靠性是降低的,且变化较平 缓;此外, $A_{10}和 A_{20}$ 对条件可靠性函数的影响效果 较为一致.

4 结论

本文对随机激励下双自由度自复位结构的首次穿越失效进行研究.首先,应用广义谐波平衡技术,将旗帜形恢复力解耦为等效刚度系数和等效阻尼系数,得到原系统的等效随机系统;然后,应用随机平均法,得到关于幅值的平均伊藤微分方程,建立并求解相应的后向 Kolmogorov(BK)方程,得到系统的条件可靠性函数和条件概率密度函数;最后,讨论了激励强度 D 与土层阻尼比 ξ_g 发生变化时对系统可靠性的影响;利用 Monte Carlo 数值模拟验证理论解析解的正确性.研究表明:

(1) 在滤波白噪声激励下,当选用金井清滤波 白噪声模型时,系统的可靠性随着激励强度的减小 以及土层阻尼比的增加而增大;

(2)随着初始幅值 A_{10} 和 A_{20} 靠近安全域,系统的可靠性降低,变化平缓;

(3)本文所用的理论分析方法得到的结果与 Monte Carlo 数值模拟结果吻合得很好.

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